

Computing Vector Addition System Reachability Sets

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Vector Addition Systems

Definition

Vector addition system (VAS) : finite set $\mathbf{A} \subseteq \mathbb{Z}^d$.

Actions : $\mathbf{a} \in \mathbf{A}$.

$$\mathbf{A} = \{\mathbf{a}_1, \mathbf{a}_2\} \text{ with } \mathbf{a}_1 = \begin{array}{|c|c|} \hline & \nearrow \\ \hline \end{array} = (-1, 1)$$

and $\mathbf{a}_2 = \begin{array}{|c|c|} \hline & \searrow \\ \hline \end{array} = (2, -1)$

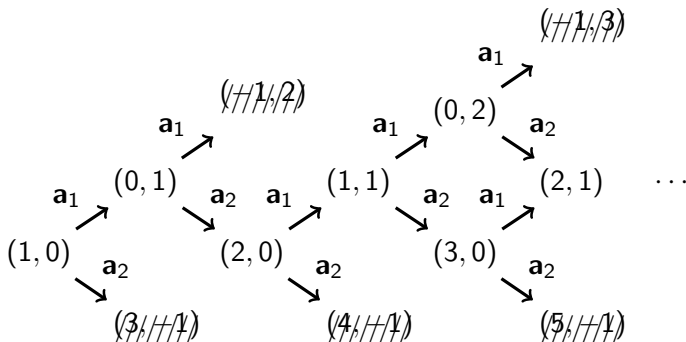
Semantics

Definition

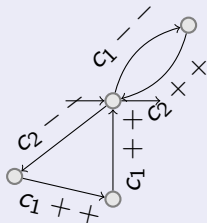
Configurations : $\mathbf{x} \in \mathbb{N}^d$.

Transition relation : $\mathbf{x} \xrightarrow{\mathbf{a}} \mathbf{y}$ if $\mathbf{x}, \mathbf{y} \in \mathbb{N}^d$, $\mathbf{a} \in \mathbf{A}$ and $\mathbf{y} = \mathbf{x} + \mathbf{a}$.

$\mathbf{A} = \{\mathbf{a}_1, \mathbf{a}_2\}$ with $\mathbf{a}_1 = \begin{array}{|c|c|} \hline & \swarrow \\ \hline \end{array} = (-1, 1)$
and $\mathbf{a}_2 = \begin{array}{|c|c|} \hline \searrow & \\ \hline \end{array} = (2, -1)$

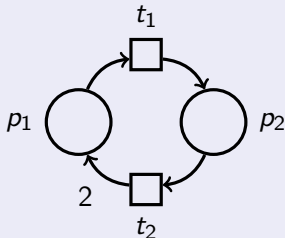


Minsky Machines without $= 0$



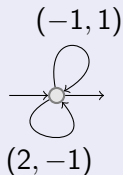
Petri nets

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VAS with states

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VAS

$$\mathbf{A} = \{(-1, 1), (2, -1)\}$$

The Reachability Problem

Reachability Problem

INPUT : **A**, a VAS
 (**c**_{init}, **c**_{final}), a pair of configurations.

OUTPUT : **c**_{init} $\xrightarrow{\mathbf{a}_1} \dots \xrightarrow{\mathbf{a}_k}$ **c**_{final} for some actions **a**₁, ..., **a**_k ?

- Many VAS Problems reduce to the VAS reachability:
 - ▶ Boundedness / Place boundedness.
 - ▶ Safety.
 - ▶ Reversibility.
 - ▶ Coverability.
 - ▶ ...
- Other problems reduce to the VAS reachability.
 - ▶ Satisfiability of some logics on data words [Bojanczyk & David & Muscholl & Schwentick & Segoufin '06 '11]
 - ▶ Software Model Checking [Heizmann & Hoenicke & Podelski '13]
 - ▶ ...

Reachability Relation

Definition

$\overset{\mathbf{a_1 \dots a_k}}{\rightsquigarrow}$ is equal to $\overset{\mathbf{a_1}}{\rightarrow} \dots \overset{\mathbf{a_k}}{\rightarrow}$

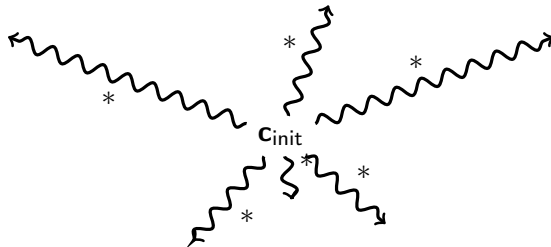
$$\overset{W}{\rightsquigarrow} = \bigcup_{w \in W} \overset{w}{\rightsquigarrow}$$

$$\overset{A^*}{\rightsquigarrow} = \overset{*}{\rightsquigarrow}$$

Reachability Sets

Definition

$$\text{Reachability set from } \mathbf{c}_{\text{init}} = \left\{ \mathbf{c} \mid \mathbf{c}_{\text{init}} \xrightarrow{*} \mathbf{c} \right\}$$



Reachability set from \mathbf{c}_{init}

=

Most precise inductive invariant containing \mathbf{c}_{init} .

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A Simple Algorithm

Reachability Semi-Algorithm:

INPUT : $(\mathbf{A}, \mathbf{c}_{\text{init}})$ initialized VAS

OUTPUT : The reachability set.

$\mathbf{C} \leftarrow \{\mathbf{c}_{\text{init}}\}$

while \mathbf{C} is not inductive

 select an action \mathbf{a}

$\mathbf{C} \leftarrow \mathbf{C} \cup \{\mathbf{c}' \mid \exists \mathbf{c} \in \mathbf{C} \ \mathbf{c} \xrightarrow{\mathbf{a}} \mathbf{c}'\}$

return \mathbf{C}

Remarks:

- Correct !
- Terminates if, and only if, the reachability set is finite.

Monotonicity

Lemma (Monotonicity)

For any configuration \mathbf{c} :

$$\begin{array}{ccc} \mathbf{c}_{init} & \xrightarrow{W} & \mathbf{c}_{final} \\ \Rightarrow & & \\ \mathbf{c}_{init} + \mathbf{c} & \xrightarrow{W} & \mathbf{c}_{final} + \mathbf{c} \end{array}$$

Proof:

$$\mathbf{x} \xrightarrow{\mathbf{a}} \mathbf{y}$$

$$\Rightarrow \mathbf{y} = \mathbf{x} + \mathbf{a}$$

$$\Rightarrow (\mathbf{y} + \mathbf{c}) = (\mathbf{x} + \mathbf{c}) + \mathbf{a}$$

$$\Rightarrow \begin{array}{cc} \mathbf{x} & \mathbf{y} \\ + & \xrightarrow{\mathbf{a}} + \\ \mathbf{c} & \mathbf{c} \end{array}$$

Example of Computation

$\mathbf{A} = \{\mathbf{a}_1, \mathbf{a}_2\}$ with $\mathbf{a}_1 = (-1, 1)$ and $\mathbf{a}_2 = (2, -1)$.
 $\mathbf{c}_{\text{init}} = (1, 0)$.

$$(1, 0) \xrightarrow{\mathbf{a}_1} (0, 1) \xrightarrow{\mathbf{a}_2} (2, 0)$$

By monotonicity $\forall n \geq 0$:

$$(n+1, 0) = \begin{pmatrix} (1, 0) \\ (n, 0) \end{pmatrix} \xrightarrow{\mathbf{a}_1 \mathbf{a}_2} \begin{pmatrix} (2, 0) \\ (n, 0) \end{pmatrix} = (n+2, 0)$$

By induction $\forall n \geq 0$:

$$(1, 0) \xrightarrow{(\mathbf{a}_1 \mathbf{a}_2)^n} (n+1, 0).$$

$$\mathbf{c}_{\text{init}} \xrightarrow{(\mathbf{a}_1 \mathbf{a}_2)^*} \mathbf{c} \iff \mathbf{c} \in (1, 0) + \mathbb{N}(1, 0)$$

$$\mathbf{c}_{\text{init}} \xrightarrow{(\mathbf{a}_1 \mathbf{a}_2)^* \mathbf{a}_1^*} \mathbf{c} \iff \mathbf{c} \in \{(1, 0), (0, 1)\} + \mathbb{N}(1, 0) + \mathbb{N}(0, 1)$$

Acceleration

Acceleration Semi-Algorithm:

INPUT : $(\mathbf{A}, \mathbf{c}_{\text{init}})$ initialized VAS

OUTPUT : The reachability set.

$\mathbf{C} \leftarrow \{\mathbf{c}_{\text{init}}\}$

while \mathbf{C} is not inductive

 select word σ

$$\mathbf{C} \leftarrow \left\{ \mathbf{c}' \mid \exists \mathbf{c} \in \mathbf{C} \quad \mathbf{c} \overset{\sigma^*}{\rightsquigarrow} \mathbf{c}' \right\}$$

return \mathbf{C}

Remarks:

- Correct !
- Implemented in tools : FAST, LASH, TREX, ...

Flat Initialized VAS

Definition (Flat Initialized VAS)

An initialized VAS $(\mathbf{A}, \mathbf{c}_{\text{init}})$ is flat if:

$$\text{Reachability set from } \mathbf{c}_{\text{init}} = \left\{ \mathbf{c} \mid \mathbf{c}_{\text{init}} \xrightarrow{\sigma_1^* \dots \sigma_k^*} \mathbf{c} \right\}$$

for some $\sigma_1, \dots, \sigma_k \in \mathbf{A}^*$.

Lemma

There exists a terminating execution of the acceleration semi-algorithm from $(\mathbf{A}, \mathbf{c}_{\text{init}})$ if, and only if, $(\mathbf{A}, \mathbf{c}_{\text{init}})$ is flat.

Deterministic Executions

Theorem

Assume that the line “select word σ ” produces an infinite sequence of words such that any finite sequence is a subsequence, then the acceleration semi-algorithm terminates from $(\mathbf{A}, \mathbf{c}_{init})$ if, and only if, $(\mathbf{A}, \mathbf{c}_{init})$ is flat.

Proof.

Just observe that $\mathbf{C} \subseteq \left\{ \mathbf{c}' \mid \exists \mathbf{c} \in \mathbf{C} \ \mathbf{c} \rightsquigarrow^{\sigma^*} \mathbf{c}' \right\}$. □

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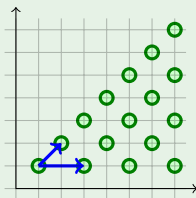
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Presburger Sets

Definition

A Presburger set is a set $\mathbf{X} \subseteq \mathbb{N}^d$ definable in $\text{FO}(\mathbb{N}, +)$.

Example



$$(1, 1) + \mathbb{N}(1, 1) + \mathbb{N}(2, 0)$$

Denoted by:

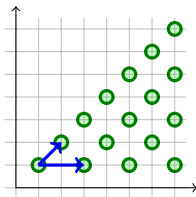
$$\phi(x, y) := \exists n_1 \exists n_2 \quad x = 1 + n_1 + 2n_2 \wedge y = 1 + n_1$$

Semilinear Sets

Definition (Ginsburg & Spanier '66)

Linear set : $\mathbf{b} + \mathbb{N}\mathbf{p}_1 + \cdots + \mathbb{N}\mathbf{p}_m$ with $\mathbf{b}, \mathbf{p}_1, \dots, \mathbf{p}_m \in \mathbb{N}^d$.

Semilinear set : finite union of linear sets.



$$(1, 1) + \mathbb{N}(1, 1) + \mathbb{N}(2, 0)$$

Presburger Sets = Semilinear Sets

Theorem (Ginsburg & Spanier '66)

Presburger sets = semilinear sets

Corollary

Semilinear sets are closed under union, intersection, complement, projection of components, ...

Some Undecidable Problems

- Given a relation $R \subseteq \mathbb{N}^d \times \mathbb{N}^d$ denoted by a Presburger formula, the following problems are undecidable:
 - ▶ R^* is Presburger ? is equal to a given Presburger relation ?
 - ▶ $\{\mathbf{y} \in \mathbb{N}^d \mid (\mathbf{c}_{\text{init}}, \mathbf{y}) \in R^*\}$ is Presburger ? is equal to a given Presburger set ?
 - ▶ A Minsky machine is Flat ? Its reachability set is Presburger ? is equal to a given Presburger set ?

Fireability

Lemma

For any word $\sigma \in \mathbf{A}^*$, there exists a unique configuration \mathbf{c}_σ such that:

$$\mathbf{x} \xrightarrow{\sigma} \iff \mathbf{x} \geq \mathbf{c}_\sigma$$

$$\mathbf{a}_1 = \begin{array}{|c|c|} \hline & \nearrow \\ \hline \end{array} = (-1, 1) \text{ and } \mathbf{a}_2 = \begin{array}{|c|c|} \hline \searrow & \\ \hline \end{array} = (2, -1).$$

$$\mathbf{x} \xrightarrow{\mathbf{a}_1 \mathbf{a}_1 \mathbf{a}_2}$$

$$\iff$$

$$\mathbf{x} \geq \mathbf{0} \quad \wedge \quad \mathbf{x} + \mathbf{a}_1 \geq \mathbf{0} \quad \wedge \quad \mathbf{x} + \mathbf{a}_1 + \mathbf{a}_1 \geq \mathbf{0} \quad \wedge \quad \mathbf{x} + \mathbf{a}_1 + \mathbf{a}_1 + \mathbf{a}_2 \geq \mathbf{0}$$

$$\iff$$

$$\mathbf{x} \geq (0, 0) \quad \wedge \quad \mathbf{x} \geq (1, -1) \quad \wedge \quad \mathbf{x} \geq (2, -2) \quad \wedge \quad \mathbf{x} \geq (0, -1)$$

$$\iff$$

$$\mathbf{x} \geq (2, 0)$$

$$\sigma = \mathbf{a}_1 \dots \mathbf{a}_k:$$

$$\begin{aligned} \mathbf{x} & \rightsquigarrow^{\sigma} \rightarrow \\ & \iff \\ \bigwedge_{0 \leq p \leq k} \mathbf{x} + \sum_{j=1}^p \mathbf{a}_j & \geq \mathbf{0} \\ & \iff \\ \mathbf{x} & \geq \mathbf{c}_{\sigma} \end{aligned}$$

where $\mathbf{c}_{\sigma}(i) = \max_{0 \leq p \leq k} -\sum_{j=1}^p \mathbf{a}_j(i)$.

Transitive Closure with Presburger Arithmetic

Theorem (Fribourg '00)

$\rightsquigarrow^{\sigma^*}$ is effectively Presburger.

$$\sigma = \mathbf{a}_1 \dots \mathbf{a}_k:$$

$$\mathbf{x} \rightsquigarrow^{\sigma^n} \mathbf{y}$$

$$\Longleftrightarrow$$

$$\mathbf{x} + n \sum_{j=1}^k \mathbf{a}_j = \mathbf{y} \text{ and } \forall 0 \leq m < n \quad \mathbf{x} + m \left(\sum_{j=1}^k \mathbf{a}_j \right) \geq \mathbf{c}_\sigma$$

Iterating Linear Functions

Theorem (Boigelot'98)

$f : \mathbb{Z}^d \rightarrow \mathbb{Z}^d$ function $f(\mathbf{x}) = M\mathbf{x} + \mathbf{v}$ where $M \in \mathbb{Z}^{d \times d}$ and $\mathbf{v} \in \mathbb{Z}^d$.

$$\mathbf{y} \in f^*(\mathbf{x})$$

is definable in $\text{FO}(\mathbb{Z}, \mathbb{N}, +)$ if, and only if,

$$M^* = \{M^n \mid n \in \mathbb{N}\}$$

is finite.

Example

Let $f(x) = 2x$. Then $y \in f^*(x) \iff \exists n \in \mathbb{N} \mid y = 2^n x$.

Iterating Guarded Linear Functions

Theorem (Leroux & Finkel '02)

$f : \mathbb{Z}^d \rightarrow \mathbb{Z}^d$ function defined over a set definable in $\text{FO}(\mathbb{Z}, \mathbb{N}, +)$ by $f(\mathbf{x}) = M\mathbf{x} + \mathbf{v}$ where $M \in \mathbb{Z}^{d \times d}$ is such that M^ is finite and $\mathbf{v} \in \mathbb{Z}^d$.*

$$\mathbf{y} \in f^*(\mathbf{x})$$

is definable in $\text{FO}(\mathbb{Z}, \mathbb{N}, +)$

Iterating Relations

Theorem (Bozga & Gîrlea & Iosif '09)

Let $R \subseteq \mathbb{Z}^d \times \mathbb{Z}^d$ defined as a conjunction of predicates of the form $\overset{+}{-}x \overset{+}{-}y \leq c$ where x, y are free variables and $c \in \mathbb{Z}$. Then R^* is definable in $\text{FO}(\mathbb{Z}, \mathbb{N}, +)$.

Example

$(x, y)R(x', y') := x' - x \leq 1 \wedge x - x' \leq -1 \wedge y' - y \leq 2 \wedge y - y' \leq -2$
Then $(x, y)R^*(x', y') := x' \geq x \wedge 2(x' - x) = (y' - y)$

Example

Acceleration for timed automata.

Acceleration

Acceleration Semi-Algorithm:

INPUT : $(\mathbf{A}, \mathbf{c}_{\text{init}})$ initialized VAS

OUTPUT : The reachability set.

$\mathbf{C} \leftarrow \{\mathbf{c}_{\text{init}}\}$

while \mathbf{C} is not inductive

 select word σ

$$\mathbf{C} \leftarrow \left\{ \mathbf{c}' \mid \exists \mathbf{c} \in \mathbf{C} \quad \mathbf{c} \overset{\sigma^*}{\rightsquigarrow} \mathbf{c}' \right\}$$

return \mathbf{C}

- In theory : terminate on any flat initialized VAS.
- In practice : find good heuristics and good symbolic representations.

Flat Counter Systems Almost Everywhere !

Theorem (Finkel & Leroux '02, Leroux & Sutre '05)

Reachability sets of flat Initialized VAS are effectively semilinear.



"Many known semilinear subclasses of counter automata are flat: reversal bounded counter machines, lossy vector addition systems with states, reversible Petri nets, persistent and conflict-free Petri nets, etc."

[Leroux & Sutre, ATVA 2005]

Theorem (Leroux '13)

An initialized VAS is flat if, and only if, its reachability set is semilinear.

Application:

- Completeness of acceleration techniques.
- Reachability semilinear \Rightarrow effectively semilinear.

Application : Distance of Reachability

Corollary

For any flat initialized VAS $\langle \mathbf{A}, \mathbf{c}_{init} \rangle$ there exists a constant m such that for every reachable configurations \mathbf{c} from \mathbf{c}_{init} , there exists:

$$\mathbf{c}_{init} \rightsquigarrow^{\sigma} \mathbf{c}$$

with $|\sigma| \leq m \cdot \|\mathbf{c} - \mathbf{c}_{init}\|_{\infty}$

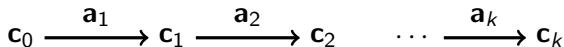
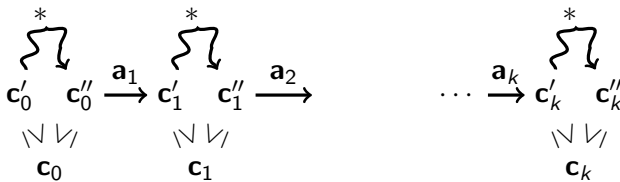
There exists $\sigma_1, \dots, \sigma_k \in \mathbf{A}^*$ such that:

$$\text{Reachability set from } \mathbf{c}_{init} = \left\{ \mathbf{c} \mid \mathbf{c}_{init} \rightsquigarrow^{\sigma_1^* \dots \sigma_k^*} \mathbf{c} \right\}$$

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Well Preorder \trianglelefteq on Runs

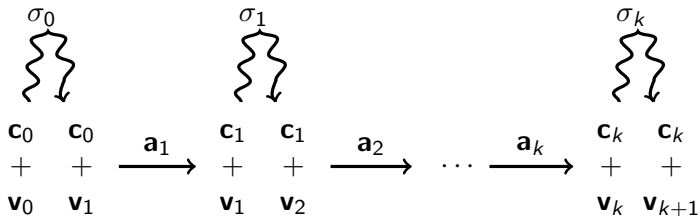


Theorem (Jančar '90, Leroux '11 '12)

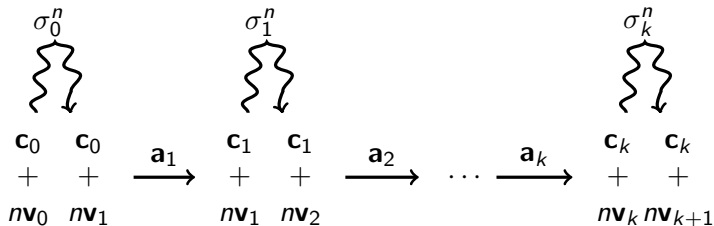
\trianglelefteq is a well preorder, i.e.:

$$\forall \rho_0, \rho_1, \dots \quad \exists i_0 < i_1 < \dots \quad | \quad \rho_{i_0} \trianglelefteq \rho_{i_1} \trianglelefteq \dots$$

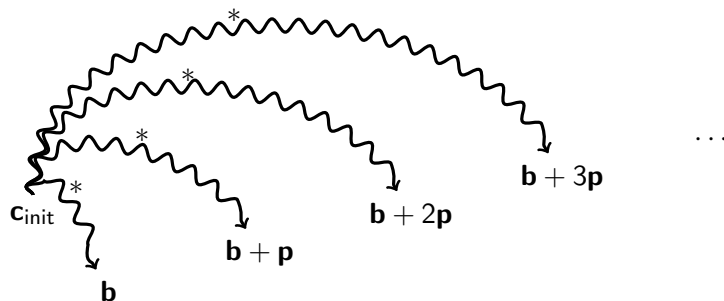
Extracting Cycles



$\Rightarrow \forall n \geq 1$



The One Period Case



$$\rho_n = (\mathbf{c}_{\text{init}} \xrightarrow{w_n} \mathbf{b} + n\mathbf{p})$$

$$\trianglelefteq \text{ well preorder} \Rightarrow \exists r \geq 0, s \geq 1 \ \rho_r \trianglelefteq \rho_{r+s}$$

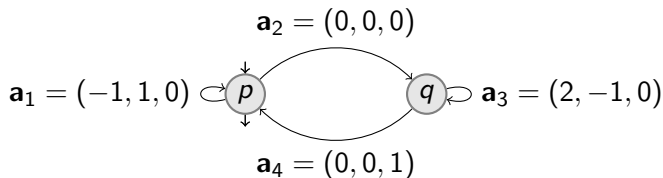
$$\exists \sigma_0, \mathbf{a}_1, \sigma_1 \dots, \mathbf{a}_k, \sigma_k \text{ such that } \forall n \in \mathbb{N}:$$

$$\mathbf{c}_{\text{init}} \xrightarrow{\sigma_0^* \mathbf{a}_1 \sigma_1^* \dots \mathbf{a}_k \sigma_k^*} \mathbf{b} + (r + ns)\mathbf{p}$$

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The Hopcroft-Pansiot 1979 Example



$$(1,0,0) \xrightarrow{\mathbf{a}_1 \mathbf{a}_2 \mathbf{a}_3 \mathbf{a}_4} (2,0,1) \xrightarrow{\mathbf{a}_1^2 \mathbf{a}_2 \mathbf{a}_3^2 \mathbf{a}_4} (4,0,2) \dots \xrightarrow{\mathbf{a}_1^{2^n} \mathbf{a}_2 \mathbf{a}_3^{2^n} \mathbf{a}_4} (2^{n+1}, 0, n+1)$$

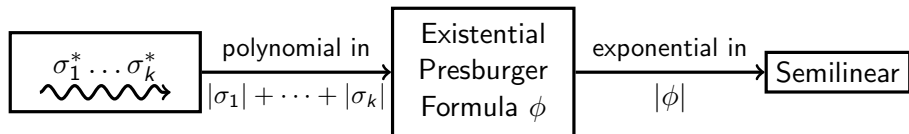
Configurations reachable from $(1, 0, 0)$

$$\{(x, y, z) \in \mathbb{N}^3 \mid 1 \leq x + y \leq 2^z\}$$

Complexity

Theorem (Mayr & Meyer '81)

There exist VAS with reachability sets of Ackermann cardinal.



Corollary

There exists semilinear VAS such that $\forall \sigma_1, \dots, \sigma_k$

$$\text{Reachability set} = \left\{ \mathbf{c} \mid \mathbf{c}_{\text{init}} \xrightarrow{\sigma_1^* \dots \sigma_k^*} \mathbf{c} \right\}$$

implies $|\sigma_1| + \dots + |\sigma_k|$ is Ackermann in the size of the VAS.

Acceleration can be combined with:

- Abstract interpretation [Gonnord & Halbwachs '10] [Leroux & Sutre '07]
- Interpolation based techniques [Hojjat & Josif & Konecny & Kuncak & Ruegger '12] [Caniart & Fleury & Leroux & Zeitoun '08]

Open Problems

Open Problems:

- \forall semilinear VAS \exists Ackermann words $\sigma_1 \dots \sigma_k$ such that:

$$\text{Reachability set} = \left\{ \mathbf{c} \mid \mathbf{c}_{\text{init}} \xrightarrow{\sigma_1^* \dots \sigma_k^*} \mathbf{c} \right\}$$

- Ackermann upper bound for semilinear VAS reachability pbm.

Facts:

- Proved for bounded VAS [McAloon '84]
- New proof based on bad sequences for the Dickson's lemma [Figueira & Figueira & Schmitz & Schnoebelen '11]

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Theorem

$$\textit{semilinear VAS} = \textit{flat VAS}$$

Observations:

- \leq is central.
- Completeness of tools based on acceleration.

Open problems:

- Complexity of the reachability problem for semilinear VAS.
 - ▶ 2 pbms !
- Simple criterion for detecting the VAS not semilinear.
- Improve acceleration techniques with on-demand over-approximations.